

Clearly, the body is in a state of plane strain. For an orthotropic material, with principal material axes  $(x_1, x_2, x_3)$  coinciding with the  $(x, y, z)$  coordinates, the stress components are given by

$$\sigma_{xz} = \sigma_{yz} = 0, \quad \sigma_{zz} = E_3 \left( \frac{\nu_{13}}{E_1} \sigma_{xx} + \frac{\nu_{23}}{E_2} \sigma_{yy} \right) \quad (11.2.3a)$$

$$\begin{Bmatrix} \sigma_{xx} \\ \sigma_{yy} \\ \sigma_{xy} \end{Bmatrix} = \begin{bmatrix} \bar{c}_{11} & \bar{c}_{12} & 0 \\ \bar{c}_{12} & \bar{c}_{22} & 0 \\ 0 & 0 & \bar{c}_{66} \end{bmatrix} \begin{Bmatrix} \varepsilon_{xx} \\ \varepsilon_{yy} \\ 2\varepsilon_{xy} \end{Bmatrix} \quad (11.2.3b)$$

where  $\bar{c}_{ij}$  are the elastic stiffnesses

$$\begin{aligned} \bar{c}_{11} &\equiv \frac{E_1(1 - \nu_{12})}{(1 + \nu_{12})(1 - \nu_{12} - \nu_{21})} \\ \bar{c}_{22} &\equiv \frac{E_2(1 - \nu_{21})}{(1 + \nu_{21})(1 - \nu_{12} - \nu_{21})} \\ \bar{c}_{12} &\equiv \nu_{12}\bar{c}_{22}, \quad \bar{c}_{66} \equiv G_{12} \end{aligned} \quad (11.2.4)$$

and  $E_1$  and  $E_2$  are principal (Young's) moduli in the  $x$  and  $y$  directions, respectively,  $G_{12}$  the shear modulus in the  $xy$  plane, and  $\nu_{12}$  and  $\nu_{21}$  the Poisson ratio (i.e., the negative of the ratio of the transverse strain in the  $y$  direction to the strain in the  $x$  direction when stress is applied in the  $x$  direction). The Poisson ratio  $\nu_{21}$  can be computed from the reciprocal relation

$$\nu_{21} = \nu_{12} \frac{E_2}{E_1} \quad (11.2.5)$$

Additional engineering constants  $E_3$ ,  $\nu_{23}$ , and  $\nu_{13}$  are required to compute  $\sigma_{zz}$ . For an isotropic material, we have

$$E_1 = E_2 = E_3 = E, \quad \nu_{12} = \nu_{21} = \nu_{13} = \nu_{23} = \nu, \quad G_{12} = G = \frac{E}{2(1 + \nu)} \quad (11.2.6)$$

The equations of motion of three-dimensional linear elasticity,  $\sigma_{ij,j} + f_i = \rho \ddot{u}_i$  with the body force components  $f_3 = f_z = 0$ ,  $f_1 = f_x = f_x(x, y)$ , and  $f_2 = f_y = f_y(x, y)$ , and  $\rho$  the density of the material, reduce to the following two plane strain equations of motion

$$\rho \frac{\partial^2 u_x}{\partial t^2} - \frac{\partial \sigma_{xx}}{\partial x} - \frac{\partial \sigma_{xy}}{\partial y} - f_x = 0 \quad (11.2.7)$$

$$\rho \frac{\partial^2 u_y}{\partial t^2} - \frac{\partial \sigma_{xy}}{\partial x} - \frac{\partial \sigma_{yy}}{\partial y} - f_y = 0 \quad (11.2.8)$$

An example of a plane strain problem is provided by the long cylindrical member under external loads that are independent of  $z$ , as shown in Fig. 11.2.1. For cross sections sufficiently far from the ends, it is clear that the displacement  $u_z$  is zero and that  $u_x$  and  $u_y$  are independent of  $z$ , i.e., a state of plane strain exists.

### 11.2.2 Plane Stress

A state of plane stress is defined as one in which the following stress field exists:

$$\begin{aligned} \sigma_{xz} = \sigma_{yz} = \sigma_{zz} &= 0 \\ \sigma_{xx} = \sigma_{xx}(x, y), \quad \sigma_{xy} = \sigma_{xy}(x, y), \quad \sigma_{yy} &= \sigma_{yy}(x, y) \end{aligned} \quad (11.2.9a)$$