Guided Tour

Chapter Introduction. Each chapter begins with an introductory section that sets up the purpose and goals of the chapter, describing in simple terms the material that will be covered and its application to the solution of engineering problems. Chapter Objectives provide students with a preview of chapter topics.

Chapter Lessons. The body of the text is divided into units, each consisting of one or several theory sections, Concept Applications, one or several Sample Problems, and a large number of homework problems. The Companion Website contains a Course Organization Guide with suggestions on each chapter lesson.

Concept Applications. Concept Applications are used extensively within individual theory sections to focus on specific topics, and they are designed to illustrate specific material being presented and facilitate its understanding.

Sample Problems. The Sample Problems are intended to show more compre-

hensive applications of the theory to the solution of engineering problems, and they employ the SMART problem-solving methodology that students are encouraged to use in the solution of their assigned problems. Since the sample problems have been set up in much the same form that students will use in solving the assigned problems, they serve the double purpose of amplifying the text and demonstrating the type of neat and orderly work that students should cultivate in their own solutions. In addition, in-problem references and captions have been added to the sample problem figures for contextual linkage to the step-by-step solution.

Homework Problem Sets. Over 25% of the nearly 1500 homework problems are new or updated. Most of the problems are of a practical nature and should appeal to engineering students. They are primarily designed, however, to illustrate the material presented in the text and to help students understand the principles used in mechanics of materials. The problems are grouped according to the portions of material they illustrate and are arranged in order of increasing difficulty. Answers to a majority of the problems are given at the end of the book. Problems for which the answers are given are set in blue type in the text, while problems for which no answer is given are set in red.



Concept Application 1.1

Considering the structure of Fig. 1.1 on page 5, assume that rod *BC* is made of a steel with a maximum allowable stress $\sigma_{aa} = 165$ MPa. Can not *BC* Sately support the load to which it will be subjected? The magnitude of the force F_{BC} in the rod was 50 kN. Recalling that the diameter of the rol is 20 mm, use Eq. (1.5) to determine the stress created in the rod by the given loading. $P = F_{BC} = +50 \text{ kN} = +50 \times 10^{8} \text{ N}$ $A = \pi r^{2} = \pi \left(\frac{20 \text{ mm}}{2}\right)^{2} = \pi (10 \times 10^{-3} \text{ m})^{2} = 314 \times 10^{-6} \text{ m}^{2}$ $\sigma = \frac{P}{314 \times 10^{-8} \text{ m}^{2}} = +159 \times 10^{6} \text{ Pa} = +159 \text{ MPa}$ Since *r* is smaller than σ_{a} of the allowable stress in the steel used, rod *BC* can safely support the load.



Chapter Review and Summary. Each chapter ends with a review and summary of the material covered in that chapter. Subtitles are used to help students organize their review work, and cross-references have been included to help them find the portions of material requiring their special attention.

Review Problems. A set of review problems is included at the end of each chapter. These problems provide students further opportunity to apply the most important concepts introduced in the chapter.



Computer Problems. Computers make it possible for engineering students to solve a great number of challenging problems. A group of six or more problems designed to be solved with a computer can be found at the end of each chapter. These problems can be solved using any computer language that provides a basis for analytical calculations. Developing the algorithm required to solve a given problem will benefit the students in two different ways: (1) it will help them gain a better understanding of the mechanics principles involved; (2) it will provide them with an opportunity to apply the skills acquired in their computer programming course to the solution of a meaningful engineering problem.



List of Symbols

a	Constant; distance
A, B, C,	Forces; reactions
A, B, C,	Points
<i>A</i> , A	Area
b	Distance; width
С	Constant; distance; radius
С	Centroid
C_1, C_2, \ldots	Constants of integration
C_P	Column stability factor
d	Distance; diameter; depth
D	Diameter
е	Distance; eccentricity; dilatation
E	Modulus of elasticity
f	Frequency; function
F	Force
<i>F.S.</i>	Factor of safety
G	Modulus of rigidity; shear modulus
h	Distance; height
Н	Force
H, J, K	Points
I, I_x, \ldots	Moment of inertia
I_{xy} ,	Product of inertia
J	Polar moment of inertia
k	Spring constant; shape factor; bulk
	modulus; constant
K	Stress concentration factor; torsional
	spring constant
l	Length; span
L	Length; span
L_e	Effective length
m	Mass
M	Couple
M, M_x, \ldots	Bending moment
M_D	Bending moment, dead load (LRFD)
M_L	Bending moment, live load (LRFD)
M_U	Bending moment, ultimate load (LRFD)
n	Number; ratio of moduli of elasticity;
	normal direction
p	Pressure
Ч	Force; concentrated load
P_D	Dead load (LRFD)

 P_L Live load (LRFD)

- P_U Ultimate load (LRFD)
- *q* Shearing force per unit length; shear flow
- **Q** Force
- *Q* First moment of area
- *r* Radius; radius of gyration
- **R** Force; reaction
- *R* Radius; modulus of rupture
- s Length
- *S* Elastic section modulus
- *t* Thickness; distance; tangential deviation
- T Torque
- *T* Temperature
- *u*, *v* Rectangular coordinates
 - *u* Strain-energy density
 - *U* Strain energy; work
 - v Velocity
 - V Shearing force
 - V Volume; shear
 - *w* Width; distance; load per unit length
- W, W Weight, load
- *x, y, z* Rectangular coordinates; distance; displacements; deflections
- $\overline{x}, \overline{y}, \overline{z}$ Coordinates of centroid
 - Z Plastic section modulus
- α, β, γ Angles
 - lpha Coefficient of thermal expansion; influence coefficient
 - γ Shearing strain; specific weight
 - γ_D Load factor, dead load (LRFD)
 - γ_L Load factor, live load (LRFD)
 - δ Deformation; displacement
 - ϵ Normal strain
 - θ Angle; slope
 - λ Direction cosine
 - ν Poisson's ratio
 - ρ Radius of curvature; distance; density
 - σ Normal stress
 - au Shearing stress
 - ϕ Angle; angle of twist; resistance factor
 - ω Angular velocity