# CONTENTS


Preface to the Fifth Edition ..... xvii
Preface to the First Edition ..... xix

**PART I KINEMATICS OF MECHANISMS ..... 1**

**Chapter 1 Introduction ..... 3**

1.0 Purpose ..... 3
1.1 Kinematics and Kinetics ..... 3
1.2 Mechanisms and Machines ..... 4
1.3 A Brief History of Kinematics ..... 5
1.4 Applications of Kinematics ..... 6
1.5 The Design Process ..... 7
*Design, Invention, Creativity ..... 7*
*Identification of Need ..... 8*
*Background Research ..... 9*
*Goal Statement ..... 10*
*Performance Specifications ..... 10*
*Ideation and Invention ..... 10*
*Analysis ..... 12*
*Selection ..... 13*
*Detailed Design ..... 13*
*Prototyping and Testing ..... 13*
*Production ..... 14*
1.6 Other Approaches to Design ..... 15
*Axiomatic Design ..... 15*
1.7 Multiple Solutions ..... 16
1.8 Human Factors Engineering ..... 16
1.9 The Engineering Report ..... 17
1.10 Units ..... 17
1.11 A Design Case Study ..... 19
*Educating for Creativity in Engineering ..... 20*
1.12 What's to Come ..... 25
1.13 Resources with This Text ..... 25
*Programs ..... 25*
*Videos ..... 25*
1.14 References ..... 26
1.15 Bibliography ..... 27

**Chapter 2 Kinematics Fundamentals ..... 30**

2.0 Introduction ..... 30
2.1 Degrees of Freedom (DOF) or Mobility ..... 30
2.2 Types of Motion ..... 31
2.3 Links, Joints, and Kinematic Chains ..... 32
2.4 Drawing Kinematic Diagrams ..... 36
2.5 Determining Degree of Freedom or Mobility ..... 37
*Degree of Freedom (Mobility) in Planar Mechanisms ..... 38*
*Degree of Freedom (Mobility) in Spatial Mechanisms ..... 40*
2.6 Mechanisms and Structures ..... 40
2.7 Number Synthesis ..... 42
2.8 Paradoxes ..... 46
2.9 Isomers ..... 47

2.10 Linkage Transformation ..... 48
2.11 Intermittent Motion ..... 53
2.12 Inversion ..... 53
2.13 The Grashof Condition ..... 55
*Classification of the Fourbar Linkage ..... 60*
2.14 Linkages of More Than Four Bars ..... 62
*Geared Fivebar Linkages ..... 62*
*Sixbar Linkages ..... 63*
*Grashof-Type Rotatability Criteria for Higher-Order Linkages ..... 63*
2.15 Springs as Links ..... 65
2.16 Compliant Mechanisms ..... 65
2.17 Micro Electro-Mechanical Systems (MEMS) ..... 67
2.18 Practical Considerations ..... 69
*Pin Joints versus Sliders and Half Joints ..... 69*
*Cantilever or Straddle Mount? ..... 71*
*Short Links ..... 72*
*Bearing Ratio ..... 72*
*Commercial Slides ..... 73*
*Linkages versus Cams ..... 73*
2.19 Motors and Drivers ..... 74
*Electric Motors ..... 74*
*Air and Hydraulic Motors ..... 79*
*Air and Hydraulic Cylinders ..... 79*
*Solenoids ..... 80*
2.20 References ..... 80
2.21 Problems ..... 81

**Chapter 3 Graphical Linkage Synthesis ..... 96**

3.0 Introduction ..... 96
3.1 Synthesis ..... 96
3.2 Function, Path, and Motion Generation ..... 98
3.3 Limiting Conditions ..... 100
3.4 Dimensional Synthesis ..... 102
*Two-Position Synthesis ..... 103*
*Three-Position Synthesis with Specified Moving Pivots ..... 109*
*Three-Position Synthesis with Alternate Moving Pivots ..... 110*
*Three-Position Synthesis with Specified Fixed Pivots ..... 111*
*Position Synthesis for More Than Three Positions ..... 117*
3.5 Quick-Return Mechanisms ..... 117
*Fourbar Quick-Return ..... 117*
*Sixbar Quick-Return ..... 119*
3.6 Coupler Curves ..... 122
3.7 Cognates ..... 132
*Parallel Motion ..... 136*
*Geared Fivebar Cognates of the Fourbar ..... 138*
3.8 Straight-Line Mechanisms ..... 139
*Designing Optimum Straight-Line Fourbar Linkages ..... 142*
3.9 Dwell Mechanisms ..... 146
*Single-Dwell Linkages ..... 146*
*Double-Dwell Linkages ..... 149*
3.10 Other Useful Linkages ..... 151
*Constant Velocity Piston Motion ..... 151*
*Large Angular Excursion Rocker Motion ..... 152*
*Remote Center Circular Motion ..... 153*
3.11 References ..... 155
3.12 Bibliography ..... 156
3.13 Problems ..... 157
3.14 Projects ..... 170

## Chapter 4 Position Analysis ..... 174

4.0 Introduction ..... 174
4.1 Coordinate Systems ..... 176
4.2 Position and Displacement ..... 176
*Position ..... 176*
*Coordinate Transformation ..... 177*
*Displacement ..... 177*
4.3 Translation, Rotation, and Complex Motion ..... 179
*Translation ..... 179*
*Rotation ..... 179*
*Complex Motion ..... 180*
*Theorems ..... 181*
4.4 Graphical Position Analysis of Linkages ..... 181
4.5 Algebraic Position Analysis of Linkages ..... 183
*Vector Loop Representation of Linkages ..... 184*
*Complex Numbers as Vectors ..... 184*
*The Vector Loop Equation for a Fourbar Linkage ..... 185*
4.6 The Fourbar Crank-Slider Position Solution ..... 192
4.7 The Fourbar Slider-Crank Position Solution ..... 194
4.8 An Inverted Crank-Slider Position Solution ..... 197
4.9 Linkages of More Than Four Bars ..... 199
*The Geared Fivebar Linkage ..... 200*
*Sixbar Linkages ..... 203*
4.10 Position of Any Point on a Linkage ..... 203
4.11 Transmission Angles ..... 204
*Extreme Values of the Transmission Angle ..... 205*
4.12 Toggle Positions ..... 207
4.13 Circuits and Branches in Linkages ..... 208
4.14 Newton-Raphson Solution Method ..... 210
*One-Dimensional Root-Finding (Newton's Method) ..... 210*
*Multidimensional Root-Finding (Newton-Raphson Method) ..... 212*
*Newton-Raphson Solution for the Fourbar Linkage ..... 213*
*Equation Solvers ..... 213*
4.15 References ..... 214
4.16 Problems ..... 214

## Chapter 5 Analytical Linkage Synthesis ..... 228

5.0 Introduction ..... 228
5.1 Types of Kinematic Synthesis ..... 228
5.2 Two-Position Synthesis for Rocker Output ..... 229
5.3 Precision Points ..... 231
5.4 Two-Position Motion Generation by Analytical Synthesis ..... 231
5.5 Comparison of Analytical and Graphical Two-Position Synthesis ..... 238
5.6 Simultaneous Equation Solution ..... 240
5.7 Three-Position Motion Generation by Analytical Synthesis ..... 242
5.8 Comparison of Analytical and Graphical Three-Position Synthesis ..... 247
5.9 Synthesis for a Specified Fixed Pivot Location ..... 252
5.10 Center-Point and Circle-Point Circles ..... 258
5.11 Four- and Five-Position Analytical Synthesis ..... 260
5.12 Analytical Synthesis of a Path Generator with Prescribed Timing ..... 261
5.13 Analytical Synthesis of a Fourbar Function Generator ..... 262
5.14 Other Linkage Synthesis Methods ..... 264
*Precision Point Methods ..... 267*
*Coupler Curve Equation Methods ..... 268*
*Optimization Methods ..... 268*
5.15 References ..... 271
5.16 Problems ..... 274

**Chapter 6 Velocity Analysis ..... 285**

6.0 Introduction ..... 285
6.1 Definition of Velocity ..... 285
6.2 Graphical Velocity Analysis ..... 288
6.3 Instant Centers of Velocity ..... 292
6.4 Velocity Analysis with Instant Centers ..... 299
*Angular Velocity Ratio ..... 301*
*Mechanical Advantage ..... 303*
*Using Instant Centers in Linkage Design ..... 305*
6.5 Centrodes ..... 307
*A "Linkless" Linkage ..... 308*
*Cusps ..... 310*
6.6 Velocity of Slip ..... 311
6.7 Analytical Solutions for Velocity Analysis ..... 315
*The Fourbar Pin-Jointed Linkage ..... 315*
*The Fourbar Crank-Slider ..... 318*
*The Fourbar Slider-Crank ..... 321*
*The Fourbar Inverted Crank-Slider ..... 322*
6.8 Velocity Analysis of the Geared Fivebar Linkage ..... 324
6.9 Velocity of Any Point on a Linkage ..... 325
6.10 References ..... 327
6.11 Problems ..... 327

**Chapter 7 Acceleration Analysis ..... 350**

7.0 Introduction ..... 350
7.1 Definition of Acceleration ..... 350
7.2 Graphical Acceleration Analysis ..... 353
7.3 Analytical Solutions for Acceleration Analysis ..... 358
*The Fourbar Pin-Jointed Linkage ..... 358*
*The Fourbar Crank-Slider ..... 362*
*The Fourbar Slider-Crank ..... 364*
*Coriolis Acceleration ..... 366*
*The Fourbar Inverted Crank-Slider ..... 368*
7.4 Acceleration Analysis of the Geared Fivebar Linkage ..... 371
7.5 Acceleration of Any Point on a Linkage ..... 372
7.6 Human Tolerance of Acceleration ..... 374
7.7 Jerk ..... 376
7.8 Linkages of N Bars ..... 379
7.9 Reference ..... 379
7.10 Problems ..... 379
7.11 Virtual Laboratory ..... 400

**Chapter 8 Cam Design ..... 401**

8.0 Introduction ..... 401
8.1 Cam Terminology ..... 402
*Type of Follower Motion ..... 402*
*Type of Joint Closure ..... 404*
*Type of Follower ..... 405*
*Type of Cam ..... 405*
*Type of Motion Constraints ..... 406*
*Type of Motion Program ..... 407*
8.2 ***S V A J*** Diagrams ..... 408
8.3 Double-Dwell Cam Design—Choosing ***S V A J*** Functions ..... 409
*The Fundamental Law of Cam Design ..... 412*
*Simple Harmonic Motion (SHM) ..... 413*
*Cycloidal Displacement ..... 414*
*Combined Functions ..... 417*

*The SCCA Family of Double-Dwell Functions* ..... 421
*Polynomial Functions* ..... 431
*Double-Dwell Applications of Polynomials* ..... 431
8.4 Single-Dwell Cam Design—Choosing ***S V A J*** Functions ..... 435
*Single-Dwell Applications of Polynomials* ..... 437
*Effect of Asymmetry on the Rise-Fall Polynomial Solution* ..... 440
8.5 Critical Path Motion (CPM) ..... 443
*Polynomials Used for Critical Path Motion* ..... 445
8.6 Sizing the Cam—Pressure Angle and Radius of Curvature ..... 452
*Pressure Angle—Translating Roller Followers* ..... 453
*Choosing a Prime Circle Radius* ..... 456
*Overturning Moment—Translating Flat-Faced Follower* ..... 457
*Radius of Curvature—Translating Roller Follower* ..... 458
*Radius of Curvature—Translating Flat-Faced Follower* ..... 462
8.7 Practical Design Considerations ..... 467
*Translating or Oscillating Follower?* ..... 467
*Force- or Form-Closed?* ..... 467
*Radial or Axial Cam?* ..... 468
*Roller or Flat-Faced Follower?* ..... 468
*To Dwell or Not to Dwell?* ..... 469
*To Grind or Not to Grind?* ..... 469
*To Lubricate or Not to Lubricate?* ..... 470
8.8 References ..... 470
8.9 Problems ..... 471
8.10 Virtual Laboratory ..... 476
8.11 Projects ..... 476

**Chapter 9 Gear Trains ..... 482**

9.0 Introduction ..... 482
9.1 Rolling Cylinders ..... 483
9.2 The Fundamental Law of Gearing ..... 484
*The Involute Tooth Form* ..... 485
*Pressure Angle* ..... 487
*Changing Center Distance* ..... 487
*Backlash* ..... 489
9.3 Gear Tooth Nomenclature ..... 489
9.4 Interference and Undercutting ..... 492
*Unequal-Addendum Tooth Forms* ..... 492
9.5 Contact Ratio ..... 494
9.6 Gear Types ..... 497
*Spur, Helical, and Herringbone Gears* ..... 497
*Worms and Worm Gears* ..... 498
*Rack and Pinion* ..... 499
*Bevel and Hypoid Gears* ..... 499
*Noncircular Gears* ..... 500
*Belt and Chain Drives* ..... 501
9.7 Simple Gear Trains ..... 503
9.8 Compound Gear Trains ..... 504
*Design of Compound Trains* ..... 505
*Design of Reverted Compound Trains* ..... 506
*An Algorithm for the Design of Compound Gear Trains* ..... 509
9.9 Epicyclic or Planetary Gear Trains ..... 513
*The Tabular Method* ..... 515
*The Formula Method* ..... 519
9.10 Efficiency of Gear Trains ..... 521
9.11 Transmissions ..... 525
9.12 Differentials ..... 529
9.13 References ..... 531

9.14 Bibliography ..... 532
9.15 Problems ..... 532

PART II DYNAMICS OF MACHINERY ..... 543

Chapter 10 Dynamics Fundamentals ..... 545

10.0 Introduction ..... 545
10.1 Newton's Laws of Motion ..... 545
10.2 Dynamic Models ..... 546
10.3 Mass ..... 546
10.4 Mass Moment and Center of Gravity ..... 547
10.5 Mass Moment of Inertia (Second Moment of Mass) ..... 549
10.6 Parallel Axis Theorem (Transfer Theorem) ..... 551
10.7 Determining Mass Moment of Inertia ..... 551
*Analytical Methods* ..... *551*
*Experimental Methods* ..... *552*
10.8 Radius of Gyration ..... 553
10.9 Modeling Rotating Links ..... 554
10.10 Center of Percussion ..... 554
10.11 Lumped Parameter Dynamic Models ..... 556
*Spring Constant* ..... *557*
*Damping* ..... *558*
10.12 Equivalent Systems ..... 559
*Combining Dampers* ..... *561*
*Combining Springs* ..... *561*
*Combining Masses* ..... *562*
*Lever and Gear Ratios* ..... *562*
10.13 Solution Methods ..... 568
10.14 The Principle of d'Alembert ..... 569
10.15 Energy Methods—Virtual Work ..... 571
10.16 References ..... 573
10.17 Problems ..... 573

Chapter 11 Dynamic Force Analysis ..... 579

11.0 Introduction ..... 579
11.1 Newtonian Solution Method ..... 579
11.2 Single Link in Pure Rotation ..... 580
11.3 Force Analysis of a Threebar Crank-Slide Linkage ..... 583
11.4 Force Analysis of a Fourbar Linkage ..... 589
11.5 Force Analysis of a Fourbar Slider-Crank Linkage ..... 595
11.6 Force Analysis of the Inverted Crank-Slider ..... 597
11.7 Force Analysis—Linkages with More Than Four Bars ..... 600
11.8 Shaking Force and Shaking Moment ..... 601
11.9 Program Linkages ..... 602
11.10 Linkage Force Analysis by Energy Methods ..... 602
11.11 Controlling Input Torque—Flywheels ..... 605
11.12 A Linkage Force Transmission Index ..... 611
11.13 Practical Considerations ..... 612
11.14 Reference ..... 614
11.15 Problems ..... 614
11.16 Virtual Laboratory ..... 627
11.17 Projects ..... 627

## Chapter 12 Balancing ..... 630

12.0 Introduction ..... 630
12.1 Static Balance ..... 631
12.2 Dynamic Balance ..... 634
12.3 Balancing Linkages ..... 639
*Complete Force Balance of Linkages ..... 639*
12.4 Effect of Balancing on Shaking and Pin Forces ..... 643
12.5 Effect of Balancing on Input Torque ..... 644
12.6 Balancing the Shaking Moment in Linkages ..... 645
12.7 Measuring and Correcting Imbalance ..... 649
12.8 References ..... 651
12.9 Problems ..... 652
12.10 Virtual Laboratory ..... 659

## Chapter 13 Engine Dynamics ..... 660

13.0 Introduction ..... 660
13.1 Engine Design ..... 662
13.2 Slider-Crank Kinematics ..... 667
13.3 Gas Force and Gas Torque ..... 673
13.4 Equivalent Masses ..... 675
13.5 Inertia and Shaking Forces ..... 679
13.6 Inertia and Shaking Torques ..... 682
13.7 Total Engine Torque ..... 683
13.8 Flywheels ..... 684
13.9 Pin Forces in the Single-Cylinder Engine ..... 685
13.10 Balancing the Single-Cylinder Engine ..... 693
*Effect of Crankshaft Balancing on Pin Forces ..... 697*
13.11 Design Trade-offs and Ratios ..... 697
*Conrod/Crank Ratio ..... 698*
*Bore/Stroke Ratio ..... 698*
*Materials ..... 699*
13.12 Bibliography ..... 699
13.13 Problems ..... 699
13.14 Projects ..... 704

## Chapter 14 Multicylinder Engines ..... 705

14.0 Introduction ..... 705
14.1 Multicylinder Engine Designs ..... 707
14.2 The Crank Phase Diagram ..... 710
14.3 Shaking Forces in Inline Engines ..... 711
14.4 Inertia Torque in Inline Engines ..... 715
14.5 Shaking Moment in Inline Engines ..... 716
14.6 Even Firing ..... 718
*Two-Stroke Cycle Engine ..... 719*
*Four-Stroke Cycle Engine ..... 721*
14.7 Vee Engine Configurations ..... 727
14.8 Opposed Engine Configurations ..... 739
14.9 Balancing Multicylinder Engines ..... 739
*Secondary Harmonic Balancing of the Four-Cylinder Inline Engine ..... 743*
*A Perfectly Balanced Two-Cylinder Engine ..... 746*
14.10 References ..... 747
14.11 Bibliography ..... 747
14.12 Problems ..... 748
14.13 Projects ..... 749

## Chapter 15 Cam Dynamics ..... 751

15.0 Introduction ..... 751
15.1 Dynamic Force Analysis of the Force-Closed Cam-Follower ..... 752
*Undamped Response* ..... *752*
*Damped Response* ..... *755*
15.2 Resonance ..... 760
15.3 Kinetostatic Force Analysis of the Force-Closed Cam-Follower ..... 763
15.4 Kinetostatic Force Analysis of the Form-Closed Cam-Follower ..... 768
15.5 Kinetostatic Camshaft Torque ..... 771
15.6 Measuring Dynamic Forces and Accelerations ..... 773
15.7 Practical Considerations ..... 777
15.8 References ..... 777
15.9 Bibliography ..... 778
15.10 Problems ..... 778
15.11 Virtual Laboratory ..... 782

## Chapter 16 Cam- and Servo-Driven Mechanisms ..... 783

16.0 Introduction ..... 783
16.1 Servomotors ..... 784
16.2 Servo Motion Control ..... 785
*Servo Motion Functions* ..... *785*
16.3 Cam-Driven Linkages ..... 786
16.4 Servo-Driven Linkages ..... 794
16.5 Other Linkages ..... 800
16.6 Cam-Driven Versus Servo-Driven Mechanisms ..... 800
*Flexibility* ..... *800*
*Cost* ..... *801*
*Reliability* ..... *801*
*Complexity* ..... *801*
*Robustness* ..... *801*
*Packaging* ..... *802*
*Load Capacity* ..... *802*
16.7 References ..... 803
16.8 Bibliography ..... 803
16.9 Problems ..... 803

## Appendices

A Computer Programs ..... 805
B Material Properties ..... 807
C Geometric Properties ..... 811
D Spring Data ..... 813
E Coupler Curve Atlases ..... 817
F Answers to Selected Problems ..... 819
G Equations for Under- or Overbalanced Multicylinder Engines ..... 835

## Index ..... 839

## DVD Catalog ..... 855